

# **XRoar 0.27**

---

Dragon and Tandy Colour Computer emulator

---



# Table of Contents

<b>Introduction .....</b>	<b>1</b>
<b>1 Getting started .....</b>	<b>2</b>
<b>2 Installation .....</b>	<b>3</b>
2.1 Mac OS X binary package .....	3
2.2 Windows binary package .....	3
2.3 Building from source code .....	3
2.4 Cross-compilation of source code .....	4
<b>3 Emulated hardware .....</b>	<b>5</b>
3.1 Emulated machines .....	5
3.2 Video hardware .....	6
3.3 Audio hardware .....	6
3.4 Keyboard .....	7
3.5 Joysticks .....	7
3.6 Cassette images .....	7
3.7 Cartridges .....	8
3.8 Floppy disk images .....	9
<b>4 User interface .....</b>	<b>11</b>
4.1 Video output .....	11
4.2 Audio output .....	11
4.3 Drive control .....	11
4.4 Tape control .....	12
4.5 Printing .....	12
4.6 Keyboard commands .....	12
4.7 Machine snapshots .....	14
4.8 Trace mode .....	14
4.9 Command line options .....	14
4.9.1 Emulated machine options .....	14
4.9.2 Emulated cartridge options .....	15
4.9.3 Options to attach files .....	15
4.9.4 Emulator interface options .....	15
4.9.5 Other options .....	16
<b>5 Supported file types .....</b>	<b>17</b>
<b>6 Firmware ROM image names .....</b>	<b>18</b>

7	Configuration file .....	19
8	Acknowledgements .....	20

## Introduction

XRoar is a Dragon emulator that runs on a wide variety of platforms. Due to hardware similarities, XRoar also emulates the Tandy Colour Computer (CoCo) models 1 & 2. Some features are:

- Emulates Dragon 32, Dragon 64, Tano Dragon, Tandy CoCo 1 & 2.
- Emulates DragonDOS, Delta and RSDOS disk systems.
- Raw and translated keyboard modes.
- Reads and writes virtual cassettes (compact ‘.cas’ files and audio files).
- Reads and writes VDK, JVC and DMK format virtual floppy diskettes.
- Save and load snapshots.

# 1 Getting started

To start, you will need to acquire (and maybe build) the software and install it. Pre-built binary packages are available from the [XRoar home page](http://www.6809.org.uk/dragon/xroar.shtml)<sup>1</sup>. If one is not available for your architecture, you will have to build from source. XRoar should build and run on any POSIX-like system for which [SDL](http://www.libsdl.org/)<sup>2</sup> is available.

You'll also need to get hold of firmware ROM images for the machine you wish to emulate. As Microsoft wrote the BASIC ROM, I don't feel comfortable offering them up myself, but they may well be obtainable elsewhere on the Web.

For instructions on installing from source or binary package, and where to put firmware images, see [Chapter 2 \[Installation\]](#), page 3.

Once you've installed XRoar, run it and an emulator screen should appear. It tries to be a Dragon 64 first, but if ROM images can't be found for that, it then tries Dragon 32 and CoCo in that order. If you just get a strange checkerboard pattern of orange and inverse 'Q' signs, it probably failed to find any ROM images - check that first.



From here you can attach tapes (‘.cas’ or ‘.wav’ files) with *Control+L*. To load a program from tape, type *CLOADM* (machine code) or *CLOAD* (BASIC). If the program does not start automatically when it has loaded (i.e., returns you to the “OK” prompt), you will have to type *EXEC* (machine code) or *RUN* (BASIC) to start it.

XRoar will make use of attached joysticks, but can also emulate them with the cursor keys and *Left Alt*. Press *Control+J* to cycle through three emulation modes: No joystick emulation (default), Left joystick, Right joystick.

<sup>1</sup> <http://www.6809.org.uk/dragon/xroar.shtml>

<sup>2</sup> <http://www.libsdl.org/>

## 2 Installation

### 2.1 Mac OS X binary package

Mount the downloaded disk image and drag the XRoar application icon into your Applications directory.

Firmware ROM images can be stored either in ‘~/Library/XRoar/Roms/’ or ‘~/XRoar/roms/’. See [Chapter 6 \[Firmware ROM image names\]](#), page 18 for filenames the emulator will search for.

XRoar can be started by double-clicking the application icon.

### 2.2 Windows binary package

First, unpack the downloaded ZIP file. A subdirectory should be created containing the main binary, supporting DLL files and documentation.

Firmware images can be copied to this directory, or in a directory called ‘*USERPROFILE*/Application Data/XRoar/roms/’. *USERPROFILE* is usually something like ‘C:/Documents and Settings/*username*’ or ‘C:/Users/*username*’. See [Chapter 6 \[Firmware ROM image names\]](#), page 18 for filenames the emulator will search for.

XRoar can be started by running ‘*xroar.exe*’ either from a file browser or the command line.

### 2.3 Building from source code

If there is no binary package for your system, you will have to build from source. Before doing so, you should ensure you have the dependencies required to build:

- **GTK+**, the GIMP toolkit, is used to provide a file requester on Linux and Unix builds. It is available from the [GTK+ home page](#)<sup>1</sup>.
- **GtkGLExt**, an OpenGL extension to GTK+. This is optional, but if present, a full GTK+ interface can be presented. Under Linux, this obviates the need for SDL entirely. It is available from the [GTK+ OpenGL Extension project page](#)<sup>2</sup>.
- **SDL**, Simple Directmedia Layer, is used for video and audio output on most supported platforms. It can be obtained from the [SDL home page](#)<sup>3</sup>.
- **libsndfile** is optional but recommended. It allows XRoar to use audio files (such as WAVs) as a source for cassette input. It is available on the [libsndfile home page](#)<sup>4</sup>.

If you use a modern Linux or Unix distribution, it’s likely that most of these packages will be installed by default, or easily available through its package management system.

The actual build process should be fairly straightforward and follows the same steps as many other software packages. Unpack the source code, change into the created source directory, run **configure** and then if everything looks good, run **make**. Example:

---

<sup>1</sup> <http://www.gtk.org/>

<sup>2</sup> <http://projects.gnome.org/gtkglext/>

<sup>3</sup> <http://www.libsdl.org/>

<sup>4</sup> <http://www.mega-nerd.com/libsndfile/>

```
$ gzip -dc xroar-0.27.tar.gz | tar xvf -  
$ cd xroar-0.27  
$ ./configure  
$ make
```

By default, `configure` will set things up to install to `/usr/local`, but this can be changed by using the `--prefix=/path/to/destination` option.

`configure` will detect any optionally supported drivers like Sun audio, OpenGL video, etc.

Once built, run `make install` to install the binary and info documentation on your system. Firmware ROM images should be placed either in your home directory under `./xroar/roms/`, or in `PREFIX/share/xroar/roms/`, where *PREFIX* is the install prefix as above.

## 2.4 Cross-compilation of source code

XRoar can be built on one platform to run on another. The Windows binary package is built like this.

To specify a cross-compile, use the `--target=TARGET` argument to `configure`. For example, to build for Windows, you might use `./configure --target=i586-mingw32`. `configure` will detect Windows headers and configure the build accordingly.



## 3 Emulated hardware

### 3.1 Emulated machines

XRoar has built-in definitions for the following machines, selectable with the ‘`-machine NAME`’ option:

```
‘dragon32’      Dragon 32 (PAL).
‘dragon64’      Dragon 64 (PAL).
‘tano’          Tano Dragon (NTSC).
‘coco’          Tandy Colour Computer (PAL).
‘cocus’         Tandy Color Computer (NTSC).
```

If no machine is specified on the command line, XRoar will try and find a good default machine to emulate based on which ROM images you have installed (see [Chapter 6 \[Firmware ROM image names\]](#), page 18). Alternatively, once started, pressing *Control+M* cycles through all the supported machine types.

Additionally extra machines can be configured, or existing ones reconfigured, with the following options:

```
‘-machine NAME’      Select existing or configure new cartridge (‘-cart help’ for list).
‘-machine-desc TEXT’ Machine description (showed in ‘-machine help’).
‘-machine-arch ARCH’ Machine architecture. One of “dragon64”, “dragon32” or “coco”.
‘-bas FILENAME’       Specify BASIC ROM to use (usually CoCo only).
‘-extbas FILENAME’    Specify Extended BASIC ROM to use.
‘-altbas FILENAME’    Specify alternate BASIC ROM (Dragon 64).
‘-nobas’              Disable BASIC.
‘-noextbas’           Disable Extended BASIC.
‘-noaltbas’           Disable alternate BASIC (Dragon 64).
‘-tv-type TYPE’       Set TV type (“pal” or “ntsc”). See Section 3.2 \[Video hardware\], page 6.
```

`-ram SIZE`

Specify amount of RAM in kilobytes

Dragon machines all contain a complete version of Extended BASIC; CoCos are able to run with a much reduced Color BASIC, with Extended BASIC being optional.

Defining extra machines is most usefully done in the configuration file. For example:

```
machine pippin
machine-desc Dragon Pippin (prototype)
machine-arch dragon32
ram 16
```

This will define a machine named “pippin” that is basically a Dragon 32 with only 16K or RAM.

## 3.2 Video hardware

The Dragon is a UK machine, and as such generates a 50Hz PAL output. The video chip targets 60Hz NTSC displays, so extra work is required to pad this out to a 50Hz signal. This is done by stopping the video chip at two points each field and generating extra scanlines.

However a US version, the Tano Dragon, exists for use with 60Hz NTSC televisions and US CoCo machines all use NTSC. When you select which machine to emulate (see [Section 3.1 \[Emulated machines\], page 5](#)), XRoar picks the appropriate mode. This can be overridden with the `-pal` or `-ntsc` command line options.

On NTSC televisions, high frequency changes in luminance create cross-colour artifacts (harmonics that interfere with the embedded chroma signal). Some games use this to their advantage, creating colours in the otherwise black and white high resolution video modes. XRoar can approximate the colours generated in these modes to varying levels of detail. The default approach is to use a 5 bit lookup table, but a faster four colour mode can be selected by running with `-ccr simple`.

NTSC machines have another peculiarity in that from reset, the video chip could settle into one of two states (180° out of phase with each other) that affected how the cross-colour interference was interpreted by the television. Games often prompt the user to “Press Enter if the screen is red” (for example) to identify which phase the machine started in. You can adjust which state it’s in by pressing **Control+A**, which cycles through three artifacted colour modes: Off, Blue-red and Red-blue.

## 3.3 Audio hardware

The Dragon can route analogue audio from three different sources: attached cartridges, the cassette port and an internal 6-bit DAC. Additionally, a PIA line is connected to the audio output stage, so manipulating that gives a single-bit sound source. XRoar supports the DAC and the single bit audio.

Rarely, a game generates audio by toggling the analogue sound select source rapidly. XRoar will cope with this, but needs to work harder. Disable support for this with the `-fast-sound` command line option.

As it is connected to the output of the analogue mux, if the single bit sound output is instead configured as an input, the analogue level will be reflected fed back. While I can’t

claim that XRoar exactly simulates the electrical characteristics, it will emulate this as a trigger level from the DAC output derived from experimentation.

### 3.4 Keyboard

The layout of the Dragon’s keyboard is a little different to that of modern PCs, so XRoar tries to approximate the Dragon’s layout on your PC keyboard as closely as possible, so that game controls will remain in usable positions. That said, they *are* different, so some compromises need to be made: *Escape* is mapped to the Dragon’s *BREAK* key and ‘ (grave / back-tick) maps to the Dragon’s *CLEAR* key. There are no good nearby PC keys that directly correspond to the Dragon’s cursor keys, so the PC’s cursors are used for these.

If you don’t use a UK keyboard, but want a close Dragon keyboard layout, you can run with the ‘-keymap CODE’ command-line option, where ‘CODE’ is a country code: “uk” (British), “us” (American), “fr” (French AZERTY) or “de” (German QWERTZ).

XRoar can also be put into “translated” keyboard mode, where characters typed on a PC keyboard are translated into the equivalent keystrokes on the Dragon. Run with the ‘-kbd-translate’ option to start with this enabled. Press *Control+Z* to toggle this mode.

The keyboards of the Dragon and Tandy CoCo are connected in the same way, but the matrix is layed out slightly differently. When you select a machine (see [Section 3.1 \[Emulated machines\]](#), page 5), the appropriate matrix layout is selected for you, but you can toggle between the two layouts by pressing *Control+K*.

Additionally, most emulator functions are currently accessed through key combinations. See [Section 4.6 \[Keyboard commands\]](#), page 12 for a list.

### 3.5 Joysticks

XRoar supports attached joysticks, or can emulate them from the keyboard.

Joystick emulation starts off disabled, but you can cycle through three states by pressing *Control+J*: Off, Left Joystick and Right Joystick. When emulating a joystick, the cursor keys control the axes and *Left Alt* maps to the fire button.

By default, the first real joystick found is mapped to the Dragon’s left joystick port, and the second real joystick to the right port. Left and right joystick mapping can be easily swapped by pressing *Control+Shift+J*.

More fine-grained mappings can be specified with the ‘-joy-left’ and ‘-joy-right’ command line options. The argument to these command consists of three pairs of numbers in the format ‘JOYSTICK-NUMBER,INDEX’. The pairs map the X axis, Y axis and fire button respectively, and the joystick number is optional if previously specified. For example, ‘-joy-left 0,1:0:0’ maps axes 1 and 0 on joystick 0 to the X and Y axis on the left emulated joystick respectively. Button 2 of joystick 0 is mapped to the left fire button.

Previous versions defaulted to a mapping suitable for using a PS2 adaptor. To get this old behaviour, use the command line options ‘-joy-left 0,3:2:0 -joy-right 0,0:1:1’.

### 3.6 Cassette images

XRoar supports three types of cassette image: ‘.cas’ files, audio files such as ‘.wav’ and ASCII text files containing BASIC programs (‘.bas’ or ‘.asc’). ‘.cas’ files contain a binary

representation of what would be loaded from tape, audio files are a recording of the tape itself, and ASCII files contain plain text that is automatically wrapped up as an ASCII BASIC file for loading.

To attach a cassette image, press **Control+L** and select it from the file requester. If instead you press **Control+Shift+L** and select a `.cas` file, XRoar can attempt to look into the file and determine whether the program is BASIC or machine code and then autorun it by typing the appropriate BASIC command(s) for you (either **CLOAD** then **RUN** or **CLOADM:EXEC**).

To create a cassette image for writing to (with **CSAVE** or **CSAVEM** for example), press **Control+W** and enter a filename. Created files will be truncated to zero length, so be careful not to overwrite any existing files with this command.

The currently open tape files used for reading and writing are distinct.

Three command line options affect how tapes are read:

The `-tape-fast` option accelerates tape loading by intercepting ROM calls and performing the action outside the emulation. Disable with `-no-tape-fast`. On by default.

The `-tape-pad` option monitors ROM calls in order to insert extra leader bytes where appropriate (long leaders when the motor is switched on, short leaders between blocks). Disable with `-no-tape-pad`.

The `-tape-pad-auto` option will, for `.cas` files, automatically switch on leader padding when insufficient initial leader bytes are found. Disable with `-no-tape-pad-auto`. On by default.

The `-tape-rewrite` option enables rewriting of anything read from the input tape to the output tape. This is useful for creating “well formed” cassette images.

Where available, these options can be changed on the fly in the GUI. See [Section 4.4 \[Tape control\]](#), page 12.

## 3.7 Cartridges

XRoar has built-in definitions for three types of cartridge, selectable with the `-cart NAME` option:

`-dragondos`

DragonDOS, official disk controller cartridge from Dragon Data Ltd.

`-delta`

Delta System, Premier Microsystems’ disk controller cartridge for the Dragon.

`-rsdos`

RSDOS, Tandy’s disk controller cartridge for use with the CoCo.

Additionally extra cartridges can be configured, or existing ones reconfigured, with the following options:

`-cart NAME`

Select existing or configure new cartridge (`-cart help` for list). If NAME is not an existing cartridge and looks like a loadable ROM image filename (`.rom` or `.dgn` filename extension), a ROM cart is defined for that filename.

`-cart-desc TEXT`

Cartridge description (showed in `-cart help`).

`'-cart-type TYPE'`

Cartridge type. A type of “rom” will define a ROM cartridge (e.g., for a game). The type can also be one of “dragondos”, “delta” or “rsdos”, which will define a cartridge with a base type according to the list above.

`'-cart-rom FILENAME'`

ROM image to load (\$C000-).

`'-cart-rom2 FILENAME'`

Second ROM image to load (\$E000-).

If no ROM is configured for a cartridge, there is a built-in list to search for each of the disk controller types. A ROM image will be required if you want to use virtual disks.

Defining extra cartridges is most usefully done in the configuration file, for example:

```
cart sdose6
cart-desc SuperDOS E6
cart-type dragondos
cart-rom sdose6
cart-rom2 dosdream
```

This will define a cartridge called “sdose6” that is basically a DragonDOS cartridge with its ROM replaced with ‘sdose6’, and an additional ROM called ‘dosdream’.

XRoar will automatically attempt to find a disk controller cartridge relevant to the current machine unless the ‘-nodos’ option is specified.

Loading a ROM image file with *Control+L* or *Control+Shift\_L* will attach a ROM cartridge.

Within the emulator, cartridges can be enabled or disabled by pressing *Control+E*. You will almost certainly want to follow this with a hard reset (*Control+Shift+R*).

## 3.8 Floppy disk images

If a disk controller cartridge is selected, XRoar supports virtual disks.

Three virtual disk formats are supported (see [Chapter 5 \[Supported file types\]](#), page 17). Of these, DMK retains the most information about the actual layout of the floppy disk, and is the only one that XRoar will recognise as containing single-density data (as used by the Delta system).

When you attach a disk, it is read into memory, and subsequent disk operations are performed on this in-memory copy. Write enable defaults to on (so write operations on the copy will work), but write back defaults to off, so updates will not be written to the disk image file. To toggle write enable, press *Control+[5-8]*, where the number to press is the drive number plus 4. To toggle write back, press *Control+Shift+[5-8]*. Even with write back enabled, image files will not be updated until the disk in a virtual drive is changed, or you quit the emulator.

Where available, these options can also be changed on the fly in the GUI. See [Section 4.3 \[Drive control\]](#), page 11.

Write back can be set to default to on with the ‘-disk-write-back’ command line option.

You can create a new blank disk in a virtual drive by pressing *Control+Shift+[1-4]*. You will be prompted for a filename, and the extension determines which type of file will be written.

## 4 User interface

### 4.1 Video output

Under the SDL user interface, three video output modules are available, selectable with the ‘`-vo MODULE`’ command line option:

- ‘`sdlgl`’      OpenGL accelerated video output.
- ‘`sdlvuv`’    YUV overlay accelerated video output.
- ‘`sdl`’        Basic unaccelerated unscalable video output.

When using OpenGL output, the ‘`-gl-filter`’ option selects a filtering method when scaling the image. ‘`-gl-filter linear`’ averages nearby pixels (blur), ‘`-gl-filter nearest`’ selects nearest neighbour pixels (hard edges) and ‘`-gl-filter auto`’ (the default) selects nearest when the image size is an exact integer multiple of the base size, otherwise selects linear.

OpenGL output might not be available if you built from source without the appropriate support. Use ‘`-vo help`’ for a list of available modules.

On slower machines, you can specify a value for frameskip with ‘`-fskip FRAMES`’. For every frame drawn to screen this amount of frames are then skipped before the next one is drawn, reducing the amount of work needed. The default is ‘`-fskip 0`’, meaning no frames are skipped.

XRoar can be started full-screen by specifying ‘`-fs`’.

### 4.2 Audio output

Specific audio modules exist for OSS, ALSA, Sun audio, Mac OS X coreaudio and PulseAudio. If none of these are available, generic SDL audio will be used.

Use of a specific module can be forced using ‘`-ao MODULE`’. Use ‘`-ao null`’ to disable audio, or ‘`-ao help`’ for a list of available modules.

For most audio modules, the ‘`-ao-rate HZ`’ option can be used to specify a sample rate in Hz. The default will usually be 44100. The ‘`-ao-buffer-ms MS`’ or ‘`-ao-buffer-samples N`’ options may be used (where supported) to set an audio buffer size, either in milliseconds or number of samples.

### 4.3 Drive control

Currently only available in the GTK+ interface. Pressing *Control+D*, or selecting “Drive Control” from the “Tool” menu will open the drive control window.

This window allows you to insert and eject disk images, and toggle their write-enable and write-back states. See [Section 3.8 \[Disks\]](#), page 9.

## 4.4 Tape control

Currently only available in the GTK+ interface. Pressing *Control+T*, or selecting “Tape Control” from the “Tool” menu will open the tape control window.

This window shows the current tape image filename and position. The input tape image is scanned, and any recognised file header blocks listed, along with their position within the image. Double clicking a filename will seek to that point in the tape image.

Certain tape options can be configured here. See [Section 3.6 \[Cassettes\]](#), page 7.

## 4.5 Printing

XRoar supports redirecting Dragon printer output to a file or pipe with the ‘*-lp-file*’ or ‘*-lp-pipe*’ option. Printed data will be sent to the appropriate stream. Pressing *Control+Shift+P* will flush the current stream by closing it (so if the stream is a pipe, the filter will complete). The stream will be re-opened when any new data is sent.

The pipe feature allows you to use useful print filters such as *enscript*, e.g., ‘*-lp-pipe “enscript -B -N r -d printer-name”*’. This will send a job to your printer, using carriage returns as line feeds (the Dragon default), each time you press *Control+Shift+P* (or exit the emulator).

## 4.6 Keyboard commands

XRoar’s user interface is currently based around [SDL](#)<sup>1</sup>. The emulator video output window is shown, and all operations are performed with keyboard combinations, usually accessed as *Control+KEY*:

*Control+[1-4]*

Insert a virtual disk into drive 1-4. See [Section 3.8 \[Disks\]](#), page 9.

*Control+Shift+[1-4]*

Insert a blank virtual disk (40TSS) into drive 1-4. See [Section 3.8 \[Disks\]](#), page 9.

*Control+[5-8]*

Toggle write enable on disk in drive 1-4. See [Section 3.8 \[Disks\]](#), page 9.

*Control+Shift+[5-8]*

Toggle write back on disk in drive 1-4. See [Section 3.8 \[Disks\]](#), page 9.

*Control+A*

Cycle through cross-colour video modes (hi-res only). See [Section 3.2 \[Video hardware\]](#), page 6.

*Control+C*

Quit emulator.

*Control+E*

Toggle DOS emulation on/off - reset to take effect. See [Section 3.8 \[Disks\]](#), page 9.

---

<sup>1</sup> <http://www.libsdl.org/>



- Control+F* Toggle full screen mode.
- Control+I* Insert a ROM cartridge. See [Section 3.7 \[Cartridges\]](#), page 8.
- Control+Shift+I* Insert a ROM cartridge, no autorun. See [Section 3.7 \[Cartridges\]](#), page 8.
- Control+J* Cycle through joystick emulation modes (None, Left, Right). See [Section 3.5 \[Joysticks\]](#), page 7.
- Control+Shift+J* Swap joystick mapping (left/right). See [Section 3.5 \[Joysticks\]](#), page 7.
- Control+K* Toggle between Dragon and CoCo keyboard layout. See [Section 3.4 \[Keyboard\]](#), page 7.
- Control+L* Load a file (see below).
- Control+Shift+L* Load a file and attempt to autorun it where appropriate.
- Control+M* Cycle through emulated machine types (resets machine). See [Section 3.1 \[Emulated machines\]](#), page 5.
- Control+Shift+P* Flush printer output. See [Section 4.5 \[Printing\]](#), page 12.
- Control+R* Soft reset emulated machine.
- Control+Shift+R* Hard reset emulated machine.
- Control+S* Save a snapshot. See [Section 4.7 \[Snapshots\]](#), page 14.
- Control+T* Open the tape control window (certain user interfaces only). See [Section 4.4 \[Tape control\]](#), page 12.
- Control+W* Attach a virtual cassette file for writing. See [Section 3.6 \[Cassettes\]](#), page 7.
- Control+Z* Enable keyboard translation mode. See [Section 3.4 \[Keyboard\]](#), page 7.
- F12* While held, the emulator will run at the maximum possible speed.

When using *Control+L* or *Control+Shift+L* to load a file, the action to be taken is determined by its extension. See [Chapter 5 \[Supported file types\]](#), page 17 for details.

XRoar still supports the use of some old keyboard commands that were used to attach specific types of file. *Control+B* and *Control+H* are synonymous with *Control+L*.

## 4.7 Machine snapshots

XRoar can save out a snapshot of the emulated machine state and read such snapshots back in later. To save a snapshot, press **Control+S**. When using **Control+L** to load a file, anything ending in `.sna` will be recognised as a snapshot.

What is included in snapshots: Selected machine architecture, complete hardware state, current keyboard map, filenames of attached disk image files.

What is *not* (yet) included: Actual disk image data (only where to find it), attached cassettes or cartridges.

## 4.8 Trace mode

XRoar contains a “trace mode”, where it will dump a disassembly of every instruction it executes to the console. Trace mode defaults to off unless you run with `-trace`. Toggle trace mode on or off with **Control+V**.

## 4.9 Command line options

Many emulator functions can be changed using keyboard shortcuts (see [Section 4.6 \[Keyboard commands\]](#), [page 12](#)), but some behaviour can also be changed from the command line.

If you run the Windows pre-built binary, you might find that emulator output gets written to a file called `stderr.txt` instead of to the console.

### 4.9.1 Emulated machine options

See [Section 3.1 \[Emulated machines\]](#), [page 5](#) for more information.

- `-machine NAME`  
Select/configure machine (`-machine help` for a list).
- `-bas FILENAME`  
Specify BASIC ROM to use (CoCo only)
- `-extbas FILENAME`  
Specify Extended BASIC ROM to use
- `-altbas FILENAME`  
Specify alternate BASIC ROM (Dragon 64)
- `-noextbas`  
Disable Extended BASIC
- `-nodos`    Disable DOS (ROM and hardware emulation)
- `-tv-type TYPE`  
Set TV type (“pal” or “ntsc”). See [Section 3.2 \[Video hardware\]](#), [page 6](#).
- `-ram SIZE`  
Specify amount of RAM in kilobytes

### 4.9.2 Emulated cartridge options

See [Section 3.7 \[Cartridges\]](#), [page 8](#) for more information.

- `'-cart NAME'`  
Select/configure cartridge (`-cart help` for list). See [Section 3.7 \[Cartridges\]](#), [page 8](#).
- `'-cart-desc TEXT'`  
Set cartridge description.
- `'-cart-type TYPE'`  
Set cartridge type (`-cart-type help` for list). Cartridge type. A type of “rom” will define a ROM cartridge (e.g., for a game). The type can also be one of “dragonidos”, “delta” or “rsdos”, which will define a cartridge with a base type according to the list above.
- `'-cart-rom FILENAME'`  
The ROM image specified will be mapped to \$C000-.
- `'-cart-rom2 FILENAME'`  
The ROM image specified will be mapped to \$E000-.

### 4.9.3 Options to attach files

- `'-load FILENAME'`  
Load or attach ‘FILENAME’. See [Chapter 5 \[Supported file types\]](#), [page 17](#).
- `'-run FILENAME'`  
Load or attach ‘FILENAME’ and attempt autorun.
- `'-lp-file FILENAME'`  
Append Dragon printer output to FILENAME.
- `'-lp-pipe COMMAND'`  
Pipe Dragon printer output to COMMAND.

### 4.9.4 Emulator interface options

- `'-ui MODULE'`  
Specify user interface module (`'-ui help'` for a list)
- `'-vo MODULE'`  
Specify video module (`'-vo help'` for a list)
- `'-gl-filter FILTER'`  
Select OpenGL texture filter (auto, linear, nearest)
- `'-ao MODULE'`  
Specify audio module (`'-ao help'` for a list)
- `'-ao-rate HZ'`  
Set audio sample rate (if supported by module)
- `'-ao-buffer-ms MS'`  
Set audio buffer size in ms (if supported)

- `'-ao-buffer-samples N'`  
Set audio buffer size in samples (if supported)
- `'-volume VOLUME'`  
Specify audio volume (0 - 100)
- `'-fast-sound'`  
Faster but less accurate sound. See [Section 3.3 \[Audio hardware\]](#), page 6.
- `'-fs'`  
Start emulator full-screen if possible.
- `'-ccr RENDERER'`  
Specify cross-colour renderer (`'-ccr help'` for list). See [Section 3.2 \[Video hardware\]](#), page 6.
- `'-fskip FRAMES'`  
Specify frameskip (default: 0). See [Section 4.1 \[Video output\]](#), page 11.
- `'-keymap CODE'`  
Select host keyboard type by country code (uk, us, fr, de). See [Section 3.4 \[Keyboard\]](#), page 7.
- `'-kbd-translate'`  
Enable keyboard translation mode. See [Section 3.4 \[Keyboard\]](#), page 7.
- `'-joy-left [XJ,] [-]XA:[YJ,] [-]YA:[FJ,]FB'`
- `'-joy-right [XJ,] [-]XA:[YJ,] [-]YA:[FJ,]FB'`  
Map a joystick.  $J$  = joystick number,  $A$  = axis number,  $B$  = button number a  
- before axis signifies inverted axis. See [Section 3.5 \[Joysticks\]](#), page 7.
- `'-tape-fast'`  
Enable fast tape loading. See [Section 3.6 \[Cassettes\]](#), page 7.
- `'-tape-pad'`  
Enable tape leader padding. See [Section 3.6 \[Cassettes\]](#), page 7.
- `'-tape-pad-auto'`  
Detect need for leader padding automatically. See [Section 3.6 \[Cassettes\]](#),  
page 7.
- `'-tape-rewrite'`  
Enable tape rewriting. See [Section 3.6 \[Cassettes\]](#), page 7.
- `'-disk-write-back'`  
Default to enabling write-back for disk images. See [Section 3.8 \[Disks\]](#), page 9.
- `'-trace'`  
Start with trace mode on. See [Section 4.8 \[Trace mode\]](#), page 14.

#### 4.9.5 Other options

- `'-h, --help'`  
Display help text and exit
- `'--version'`  
Output version information and exit

## 5 Supported file types

XRoar can do useful things with a variety of file types. The type of a file is determined by its extension. Supported file extensions are:

Extension	Description	Read/write?
.dmk	Disk image file in a format defined by David Keil. They store a lot of information about the structure of a disk and support both single and double density data. All disk images are manipulated internally in (near enough) this format. See <a href="#">Section 3.8 [Disks]</a> , page 9.	Read & write
.jvc	Disk image file in a basic sector-by-sector format with optional header information. See <a href="#">Section 3.8 [Disks]</a> , page 9.	Read-only
.dsk		
.vdk	Another disk image file format. See <a href="#">Section 3.8 [Disks]</a> , page 9.	Read-only
.bin	Binary file (DragonDOS or CoCo). XRoar can load these directly into memory and optionally autorun them.	Read-only
.sna	XRoar snapshot. Contains a complete dump of RAM from a running emulator session along with information like which machine was being emulated, what DOS was attached, etc. See <a href="#">Section 4.7 [Snapshots]</a> , page 14.	Read & write
.hex	Intel hex record. An ASCII format that encodes binary data and where in memory to load it.	Read-only
.cas	Cassette file. Simple binary representation of data contained on a tape. Cannot represent silence, or some custom encodings. See <a href="#">Section 3.6 [Cassettes]</a> , page 7.	Read & write
.wav	Cassette audio file. XRoar can read sampled audio from original cassettes. Actually, as audio input uses libsndfile, any file with an unknown extension is passed to libsndfile to see if it recognises it as an audio file. See <a href="#">Section 3.6 [Cassettes]</a> , page 7.	Read-only
.rom	This represents two things: when starting, XRoar looks for firmware ROM images with this extension. When subsequently told to load one, however, they are assumed to be dumps of cartridge ROMs. See <a href="#">Section 3.7 [Cartridges]</a> , page 8.	Read-only

In general, to load or attach a file, press **Control+L** and choose a file from the requester that appears. What XRoar does with it will depend on its file extension. You can also automatically attach (and optionally start) files from the command line by using the ‘**-load FILE**’ or ‘**-run FILE**’ options. If you ‘**-load**’ or ‘**-run**’ a cassette image, XRoar will automatically disable any DOS cartridge emulation for you, as this can interfere with some cassette-based games. In addition, the first non-option argument to XRoar is taken as a filename and treated as though it were the argument to the ‘**-run**’ option.

## 6 Firmware ROM image names

XRoar searches for ROM images in a variety of locations. See [Chapter 2 \[Installation\]](#), [page 3](#) for where your particular platform will search. The search path can be overridden by including a colon-separated list of paths in the `XROAR_ROM_PATH` environment variable.

Images are expected to have certain names. Here's a table showing the names it searches for each ROM in each system. ROM images can have either a `.rom` or a `.dgn` extension. `.dgn` files contain a 16 byte header, which is ignored.

Machine	ROM search order	Description
dragon32	d32	Dragon BASIC.
	dragon32	
	d32rom	
	dragon	
dragon64 tano	d64_1	32K-mode Dragon BASIC.
	d64rom1	
	dragrom	
	dragon	
	d64_2	64K-mode Dragon BASIC.
	d64rom2	
	bas13	
	bas12	
coco cocous	bas11	Color BASIC 1.3, 1.2, 1.1 or 1.0.
	bas10	
	extbas11	
	extbas10	
		Extended Color BASIC 1.1 or 1.0.

Further, emulating a floppy drive controller cartridge requires that you have an image of the DOS ROM that would have been part of it.

Controller type	ROM search order	Description
dragonDOS	dplus49b	DragonDOS (using DOSplus, SuperDOS or original DragonDOS ROM).
	dplus48	
	sdose6	
	sdose5	
	sdose4	
	ddos40	
	ddos15	
	ddos10	
delta	delta	Delta System.
	deltados	
rsdos	disk11	Disk Extended Color BASIC 1.1 or 1.0.
	disk10	

## 7 Configuration file

All command-line options can also be used as directives in a configuration file called `'xroar.conf'`. This file is searched for in a variety of locations:

System	Search order
Unix	Current working directory
Mac OS X	<code>'~/xroar/'</code> <code>'~/Library/XRoar/'</code> <code>'PREFIX/share/xroar/'</code>
Windows	Current working directory <code>'~/Local Settings/Application Data/XRoar/'</code> <code>'~/Application Data/XRoar/'</code>

`'~'` indicates the user's home directory. On Unix systems this is held in the `HOME` environment variable (often `'/home/username'`), on Windows systems it is in the `USERPROFILE` environment variable (often `'c:/Documents and Settings/username'` or `'c:/Users/username'`). `PREFIX` is the installation prefix, usually `'/usr/local'`.

Directives are listed one per line without the leading dashes of the command line option.

## 8 Acknowledgements

I made reference to the MAME 6809 core for clues on how the overflow bit in the condition code register was handled.

Thanks to all the people on the [Dragon Archive Forums](http://archive.worldofdragon.org/phpBB3/)<sup>1</sup> for helpful feedback and insight.

---

<sup>1</sup> <http://archive.worldofdragon.org/phpBB3/>